

Lecture 1: Unsupervised Learning; Clustering with k -means and k -medoids

Lester Mackey

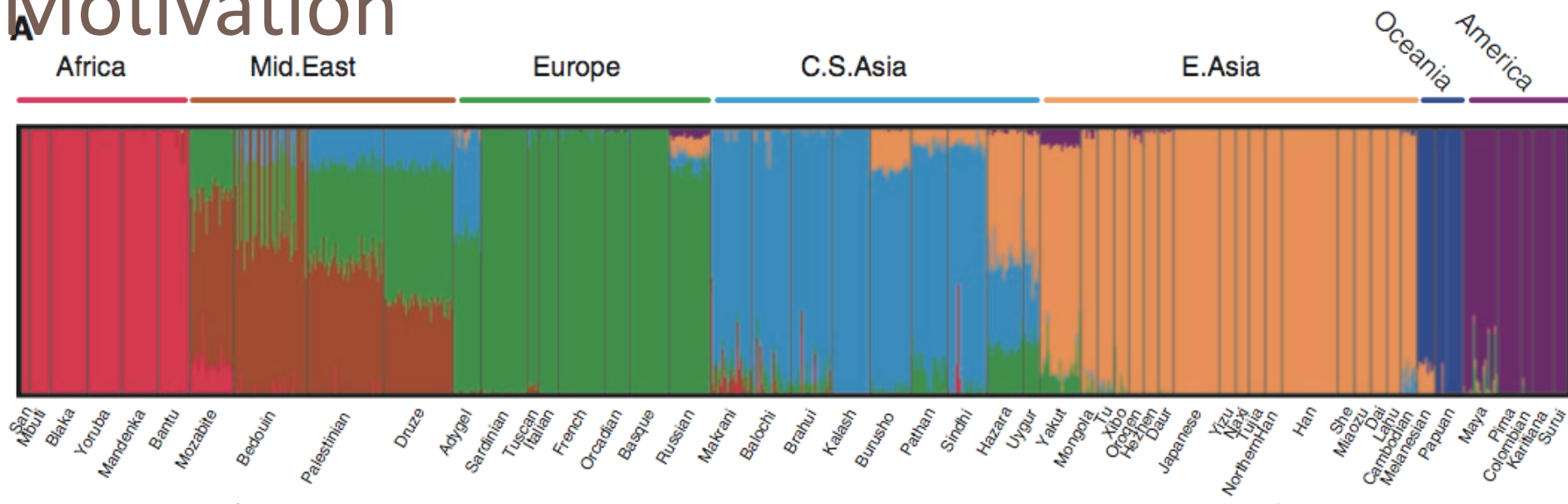
March 31, 2014

Motivation

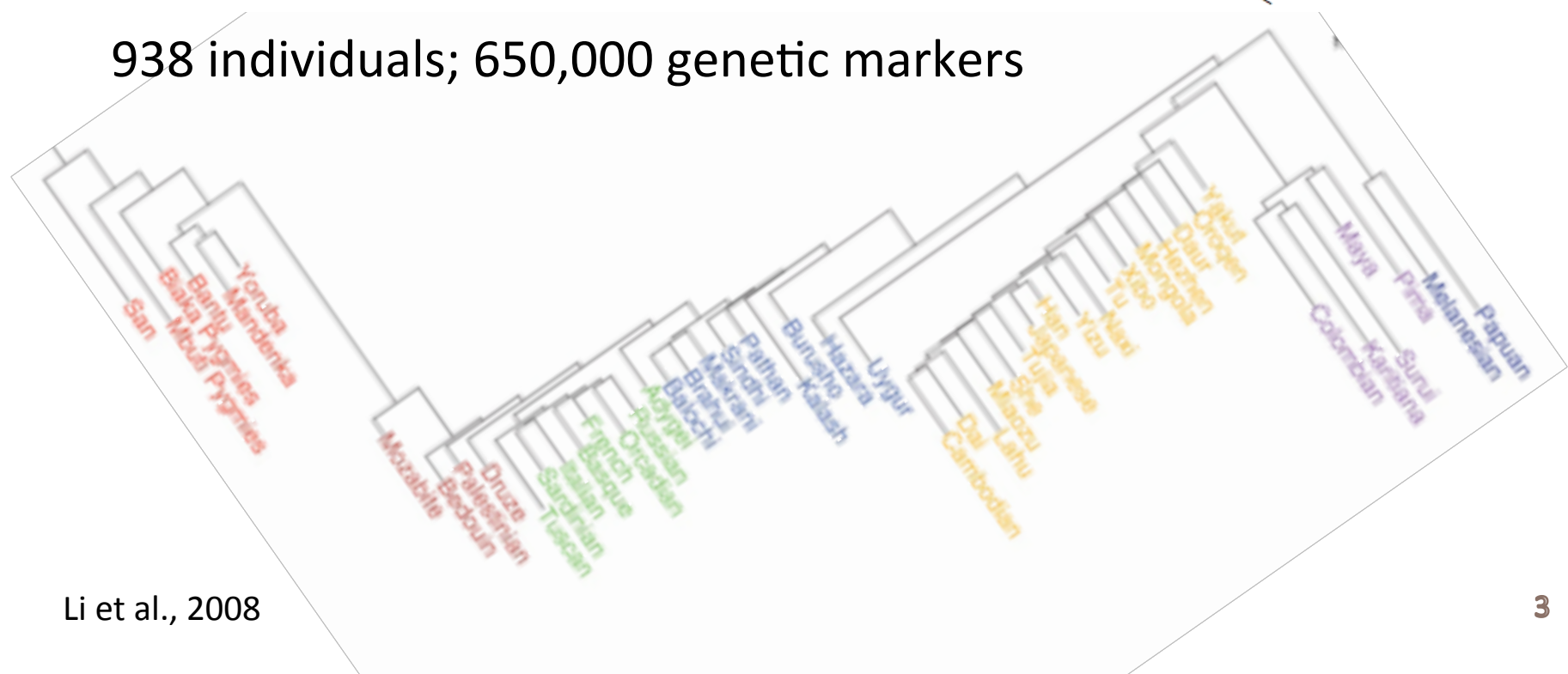
- World is filled with data of **increasing size** and **complexity**
- Much of it has underlying **low-dimensional structure**



A Motivation

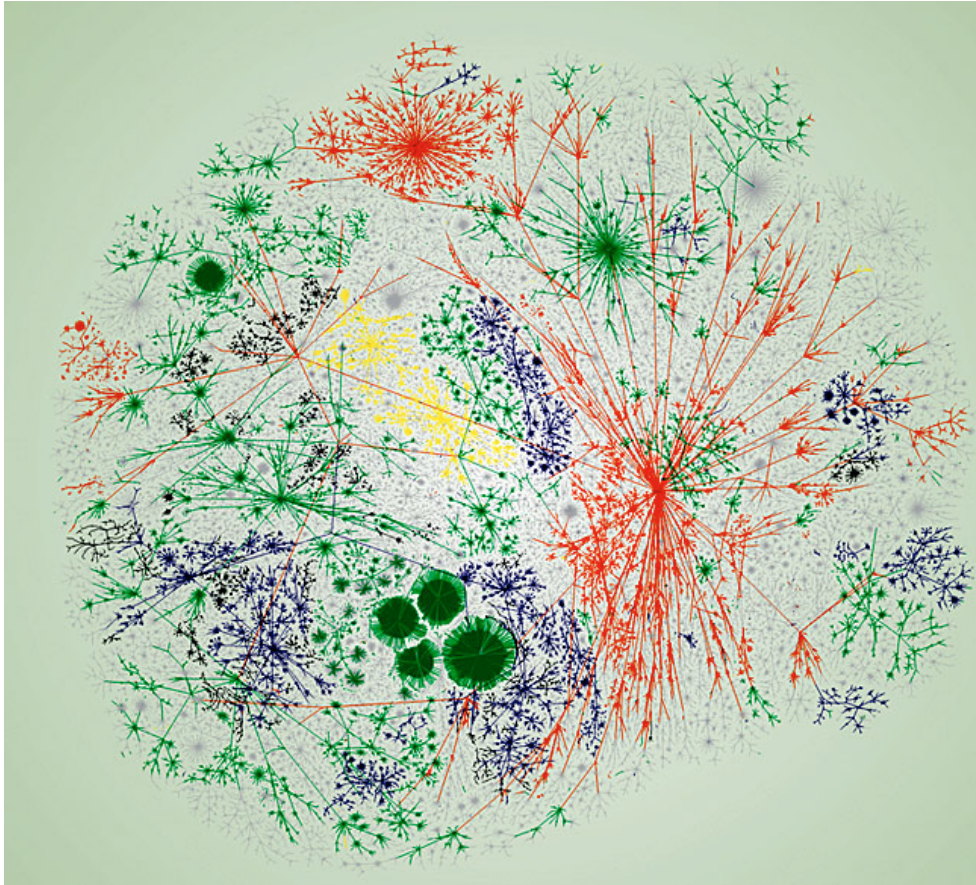


938 individuals; 650,000 genetic markers



Motivation

- World is filled with data of **increasing size** and **complexity**
- Much of it has underlying **low-dimensional structure**



Newman, 2008




- **How do we uncover the hidden structure in our data?**⁴

Unsupervised learning

Supervised learning

- Given datapoints x_1, \dots, x_n with labels y_1, \dots, y_n , learn to predict the label y_{new} associated with each new input x_{new}

- Classification:**

Chair  Primate  Which is this? 

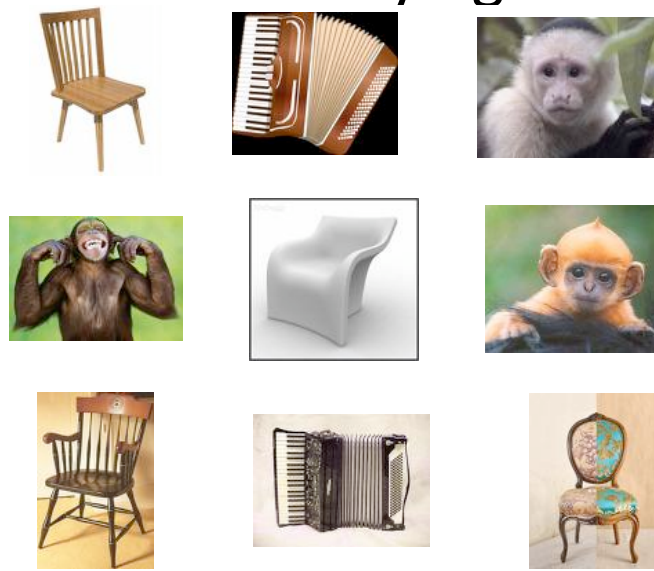
Unsupervised learning

- Given **only** x_1, \dots, x_n , infer some underlying structure

- Clustering:**

Group these unlabeled images into three classes

- Evaluation much more challenging!



Why do unsupervised learning?

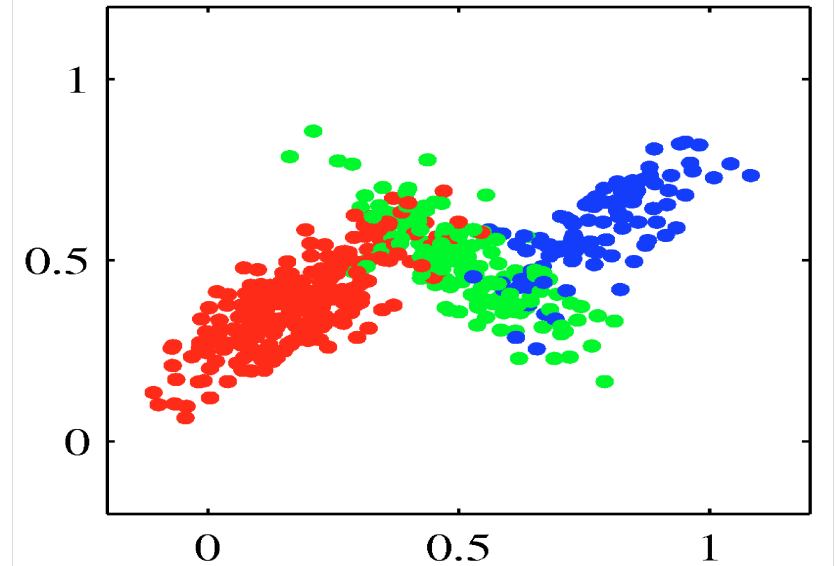
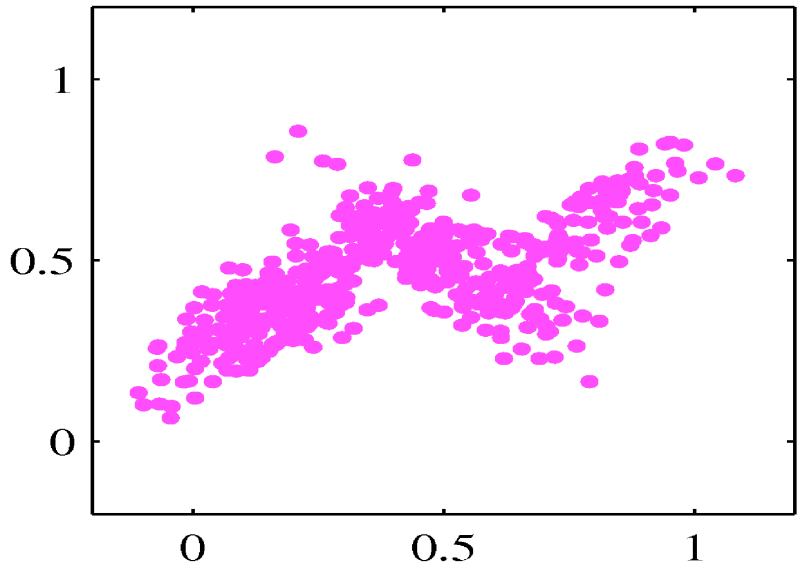
- Labeled data often **expensive** or **difficult to collect**;
Unlabeled data **abundant** and **cheap**
- Develop compressed representations to save storage and computation
- Reduce noise, missingness, irrelevant attributes in high-dimensional data
- Visualization and exploratory data analysis
- As a preprocessing step for supervised learning

This Course

- Survey of unsupervised learning methods, their properties, and their applications
- Classical paradigms
 - I. Clustering and latent class methods
 - II. Dimensionality reduction and latent feature methods
- Modern topics (based on time and interest)
 - Unsupervised learning with missing data
 - Sparse / interpretable unsupervised learning
 - Nonnegative matrix factorization, Document topic modeling
 - Subspace clustering
 - Method of moments for latent variable models
 - Unsupervised deep learning

Clustering

- **Goal:** Segment data into groups of similar points



- **Examples**

- Segment pixels in an image by object
 - Group network participants into communities
 - Identify cancer subtypes from gene expression patterns
- Will discuss many approaches to clustering in Stats306B
 - Begin with one of the simplest and most popular: **k-means**⁸

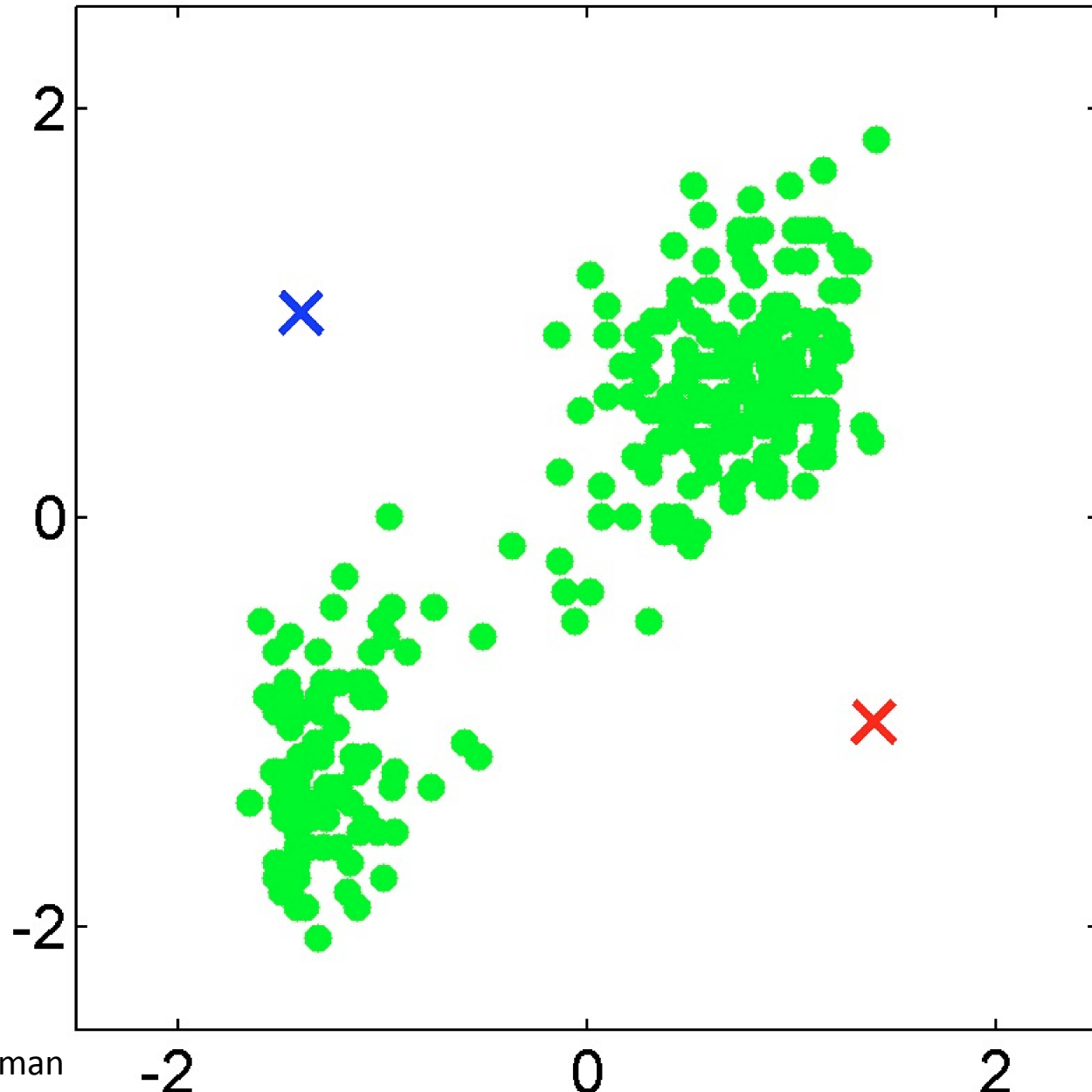
k-means

- **Summary:** Assign each datapoint to one of k clusters so that on average each point is close to its cluster mean
- **Notation**
 - Datapoint $x_i \in \mathbb{R}^p$
 - Cluster mean $m_j \in \mathbb{R}^p$
 - Cluster assignment $z_i \in \{1, \dots, k\}$
- **Objective:** $J(z_{1:n}, m_{1:k}) = \sum_{i=1}^n \|x_i - m_{z_i}\|_2^2$
- **Goal:** Minimize J over $z_{1:n}$ and $m_{1:k}$

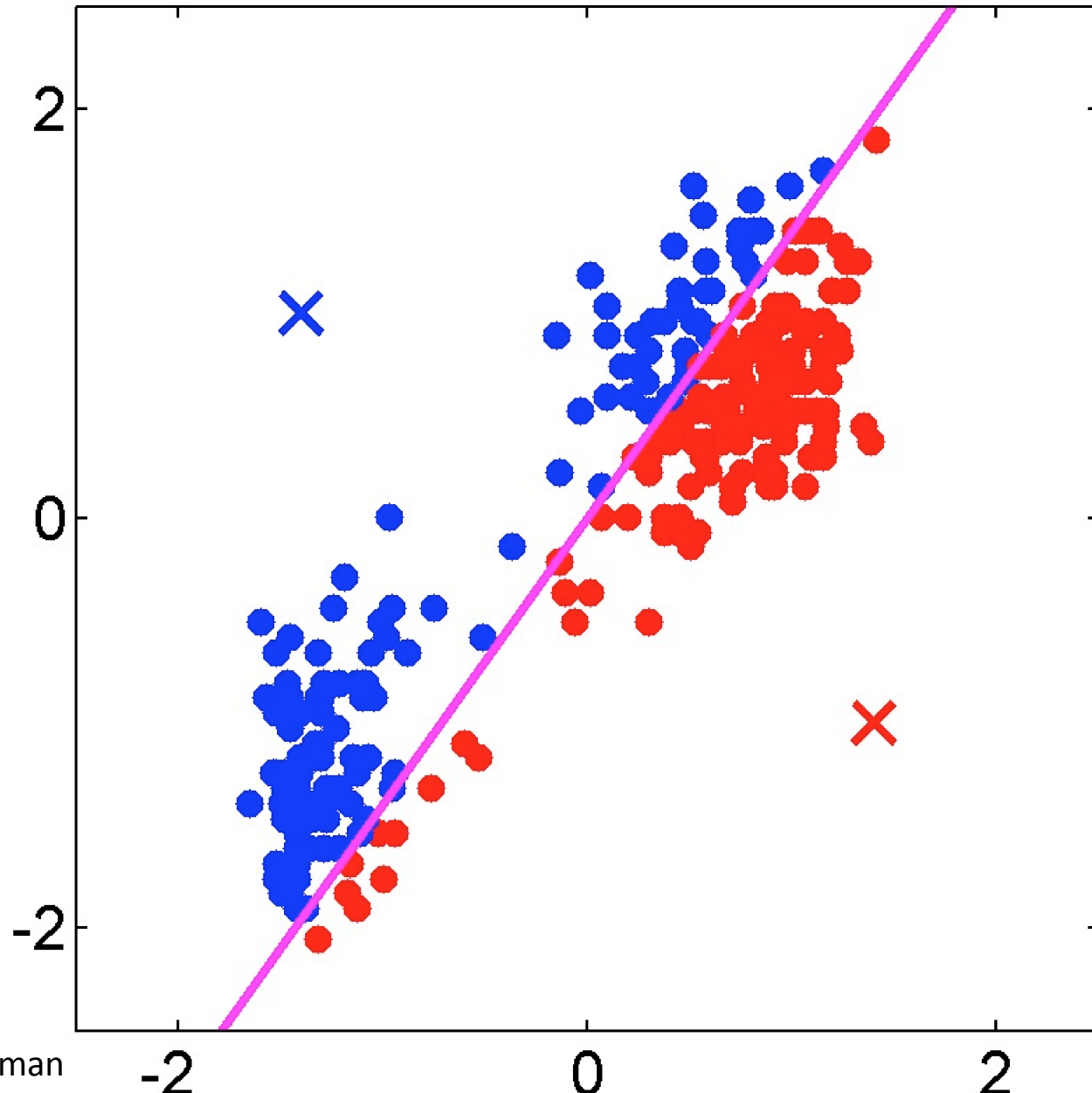
k-means

- **Goal:** Minimize $J(z_{1:n}, m_{1:k}) = \sum_{i=1}^n \|x_i - m_{z_i}\|_2^2$ over $z_{1:n}$ and $m_{1:k}$
 - Datapoint $x_i \in \mathbb{R}^p$
 - Cluster mean $m_k \in \mathbb{R}^p$
 - Cluster assignment $z_i \in \{1, \dots, k\}$
- **Standard k-means algorithm / Lloyd's algorithm**
 - Initialize cluster means arbitrarily (e.g., sample from datapoints)
 - Alternate until convergence
 - * Update cluster assignments: $z_{1:n} \leftarrow \arg \min_{z_{1:n}} J(z_{1:n}, m_{1:k})$
 - i.e., assign each point to the cluster with closest mean
 - * Update cluster means: $m_{1:k} \leftarrow \arg \min_{m_{1:k}} J(z_{1:n}, m_{1:k})$
 - i.e., $m_j = \frac{\sum_{i=1}^n \mathbb{I}(z_i=j)x_i}{\sum_{i=1}^n \mathbb{I}(z_i=j)}$, the mean of points in cluster j

Example: 2-means, Lloyd's algorithm

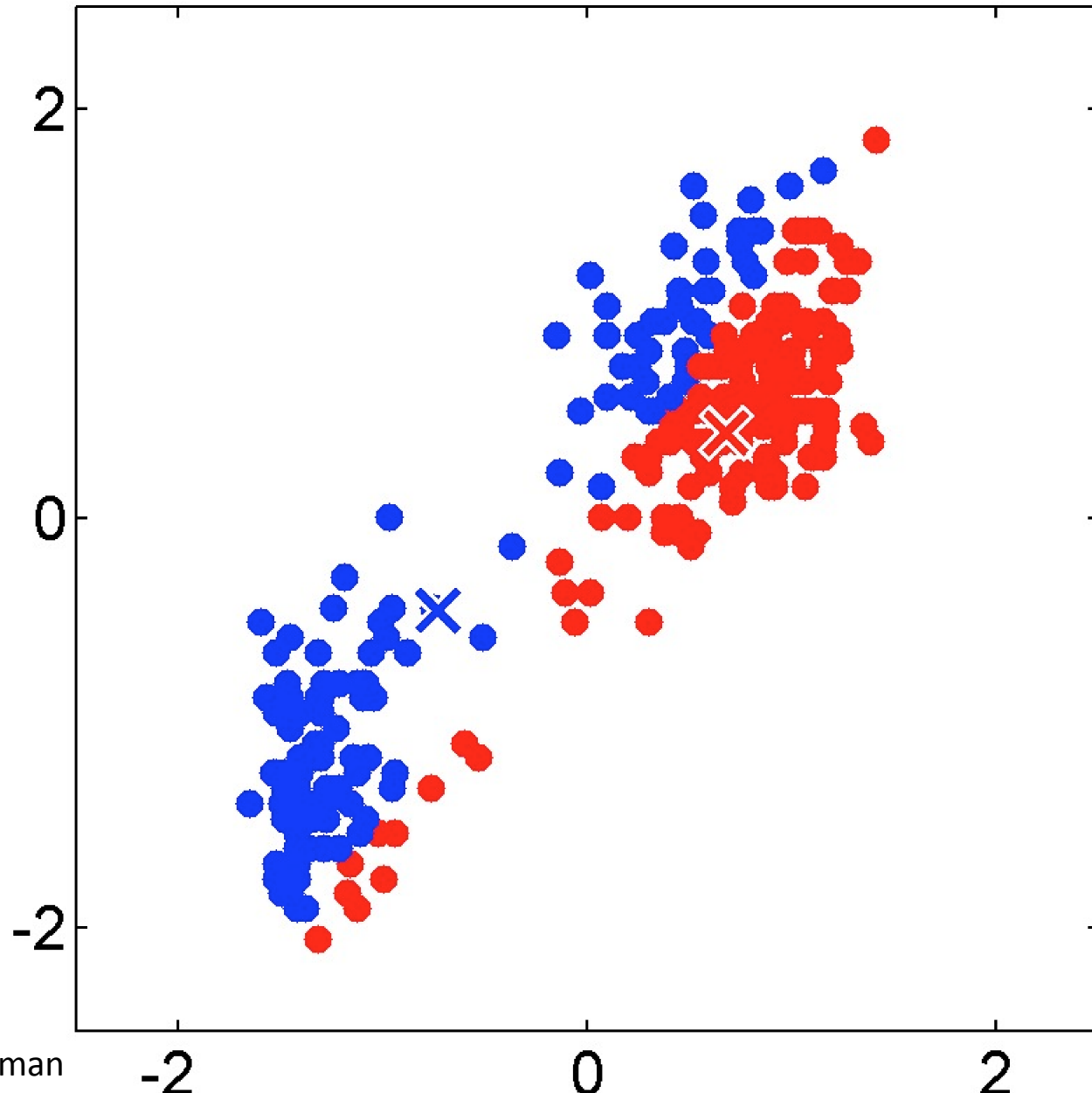


Example: 2-means, Lloyd's algorithm



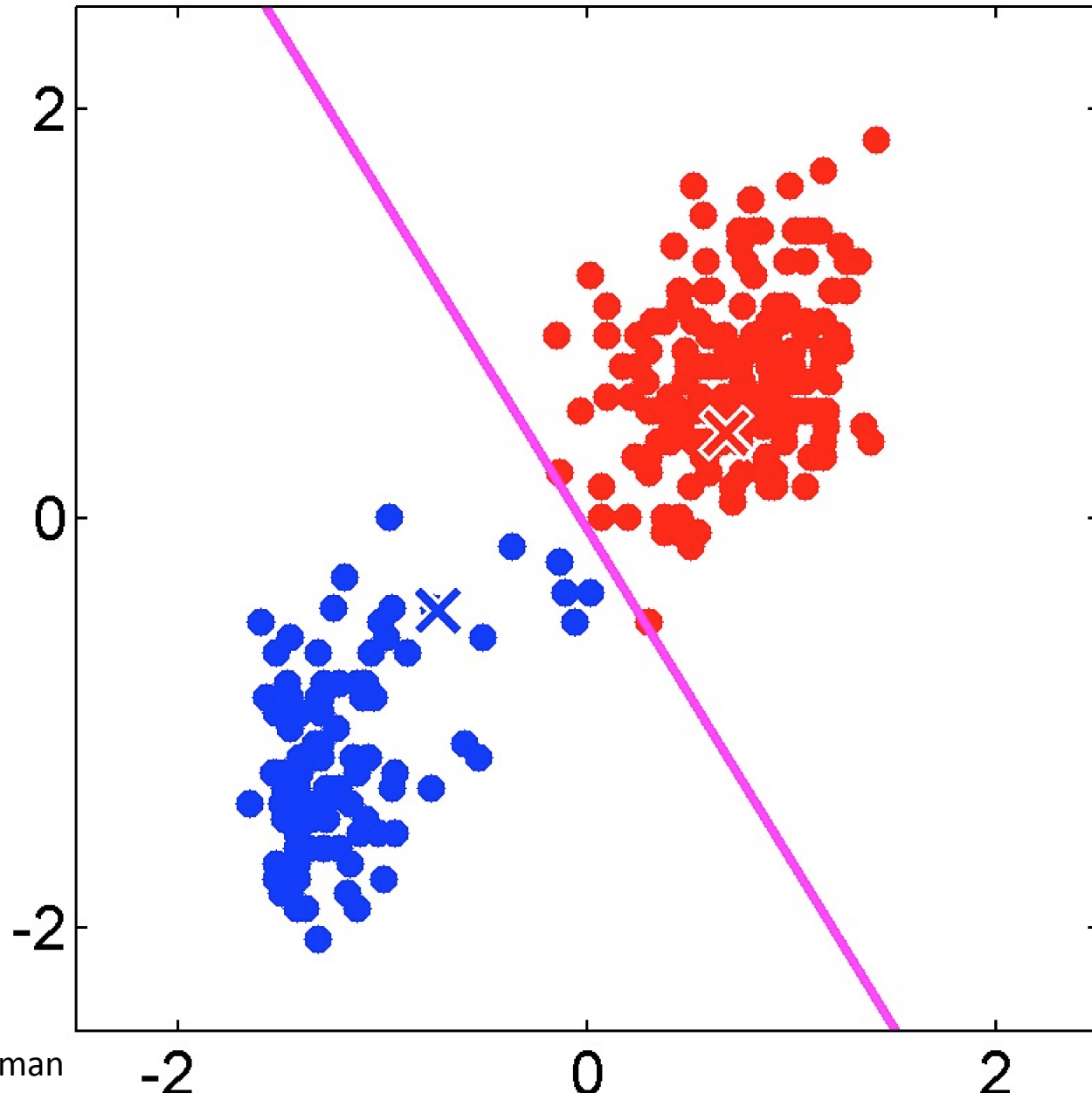
Courtesy of
Sriram Sankararaman

Example: 2-means, Lloyd's algorithm



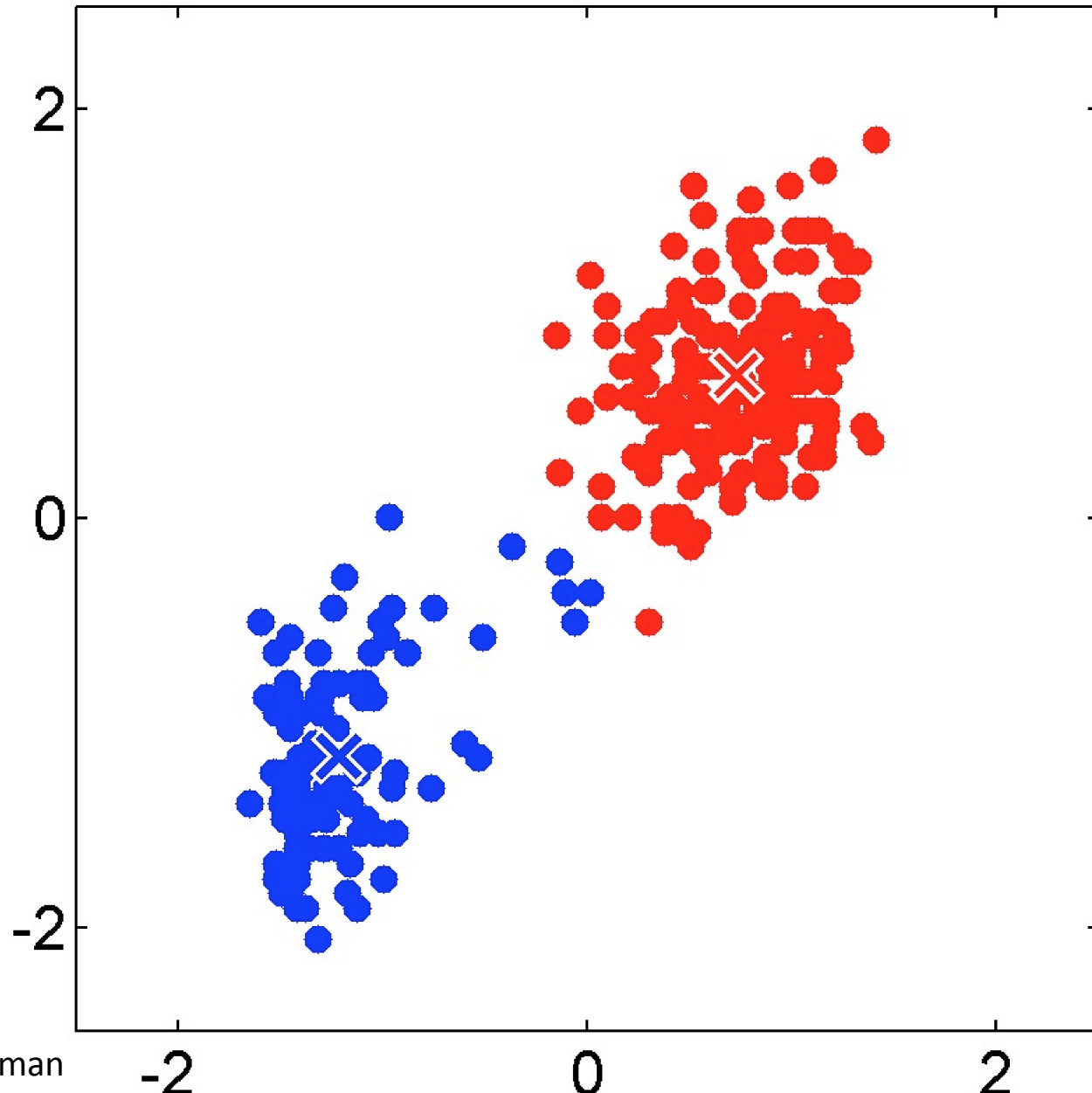
Courtesy of
Sriram Sankararaman

Example: 2-means, Lloyd's algorithm



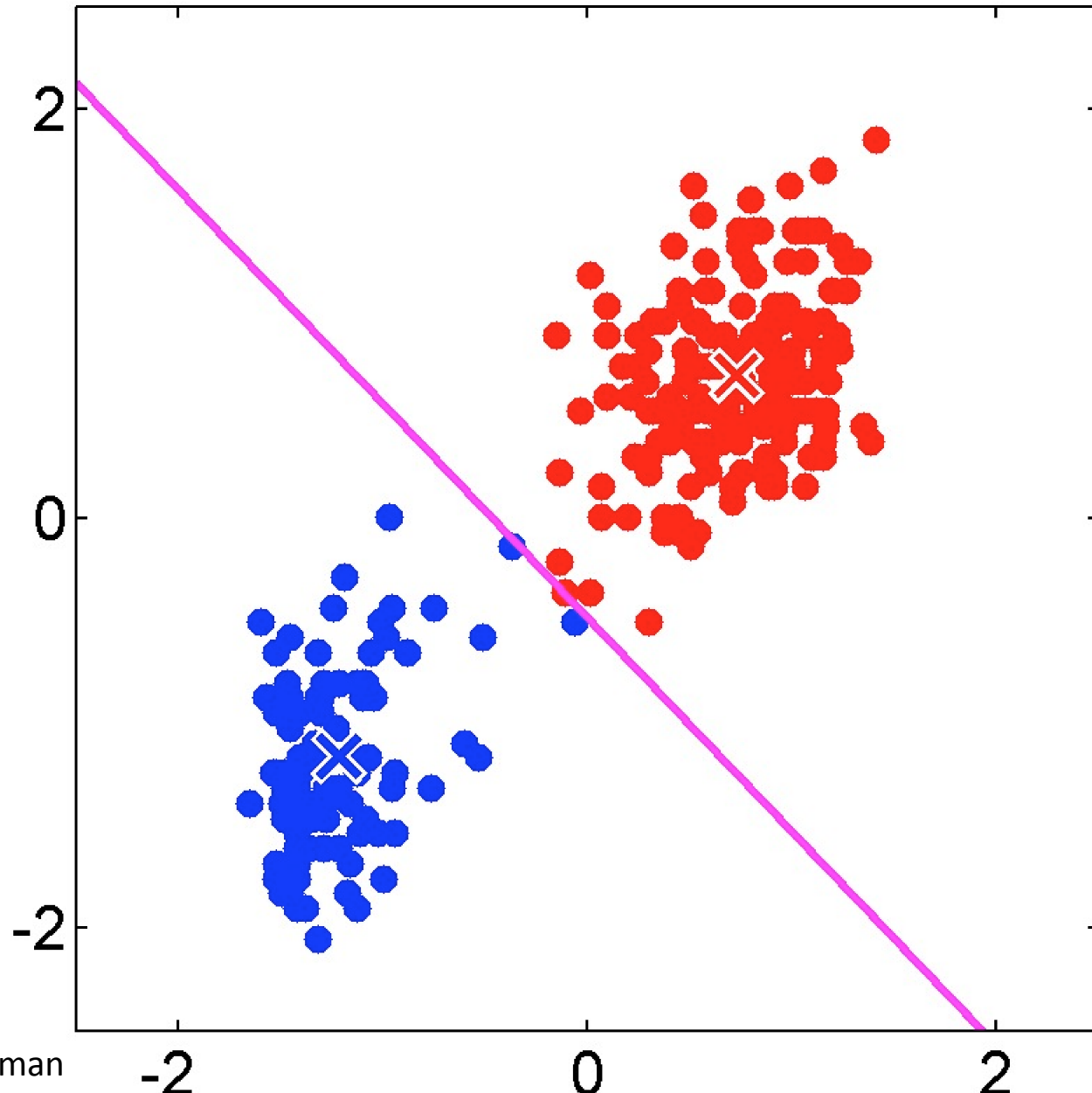
Courtesy of
Sriram Sankararaman

Example: 2-means, Lloyd's algorithm



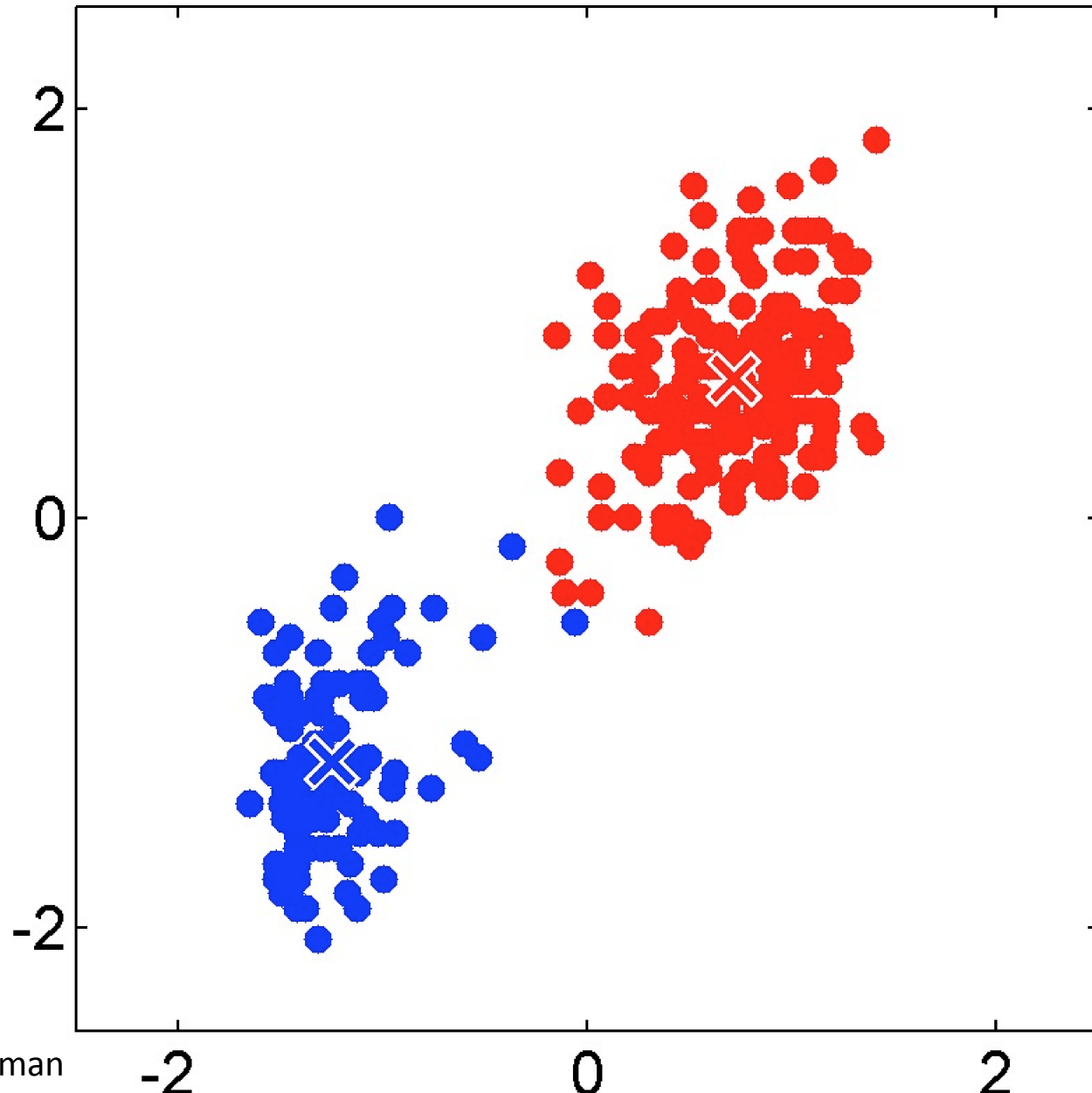
Courtesy of
Sriram Sankararaman

Example: 2-means, Lloyd's algorithm



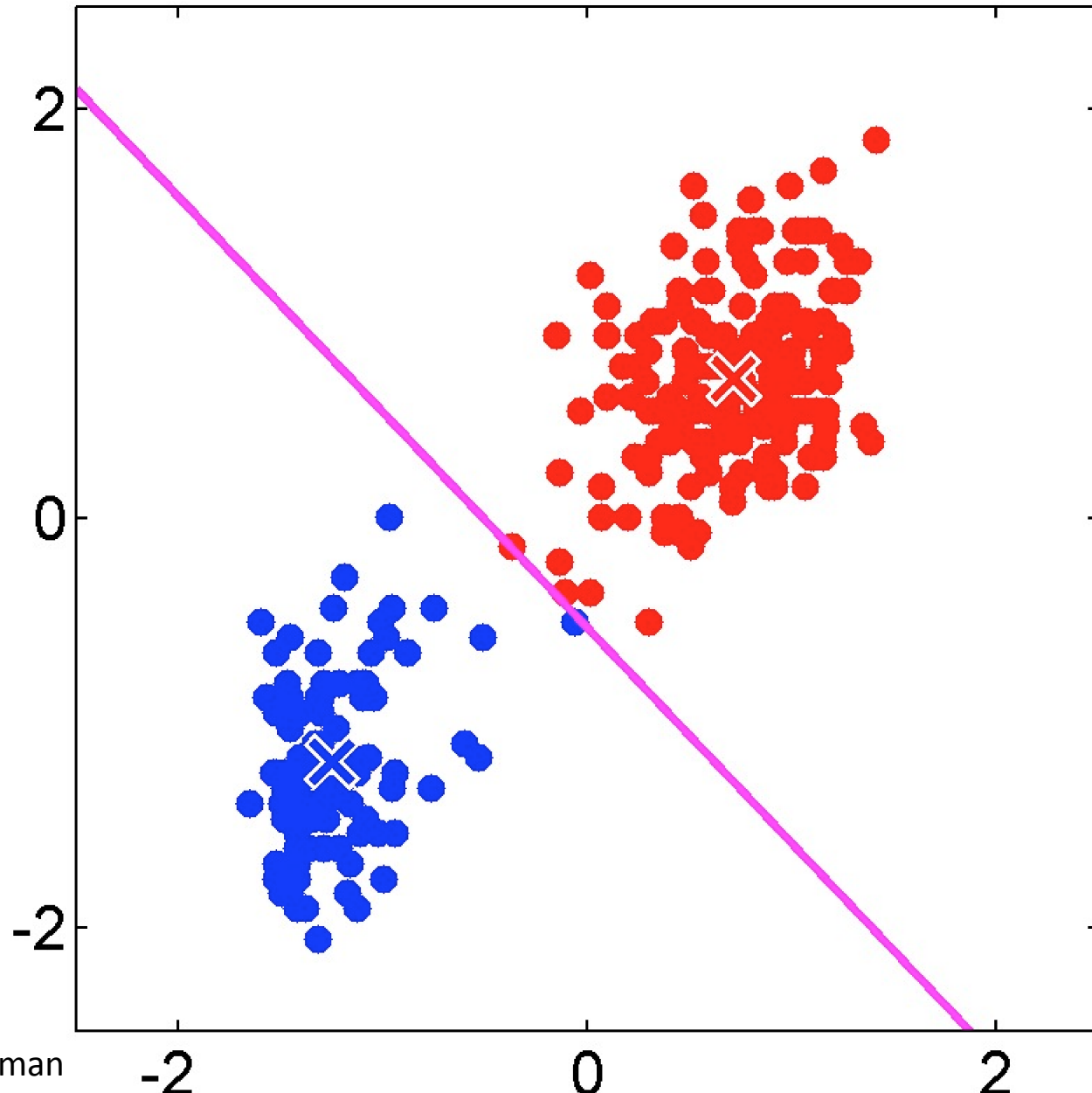
Courtesy of
Sriram Sankararaman

Example: 2-means, Lloyd's algorithm



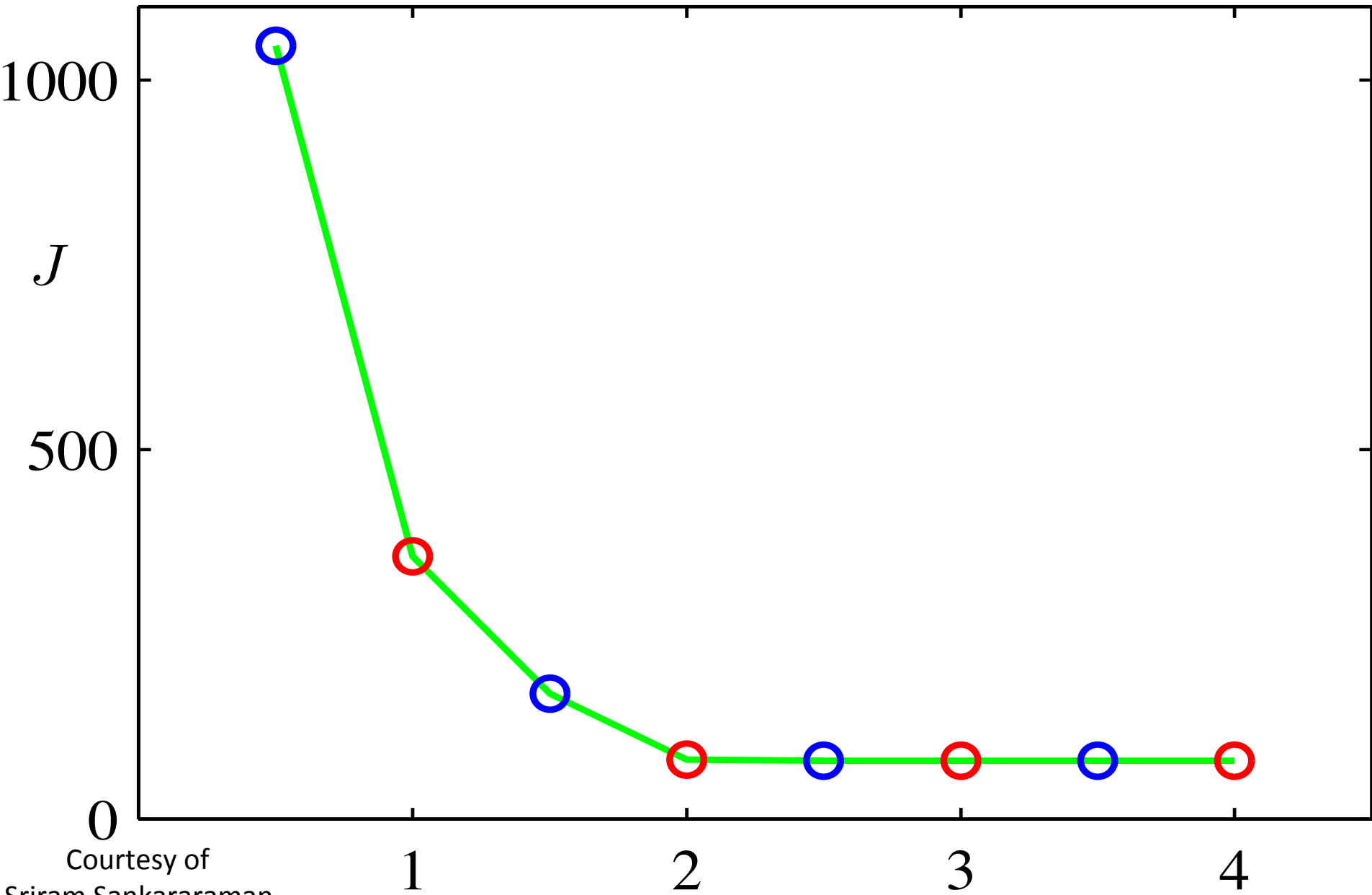
Courtesy of
Sriram Sankararaman

Example: 2-means, Lloyd's algorithm



Courtesy of
Sriram Sankararaman

Objective function J after each iteration



Courtesy of
Sriram Sankararaman

Does Lloyd's algorithm always converge?

- The objective J **always converges**
 - Lloyd's algorithm is a coordinate descent procedure
 - Each step monotonically decreases objective
 - Only finite number of partitions of data, so objective must converge in finite number of steps
- Technically, **algorithm could cycle** if ties arise (i.e., if multiple centroids equidistant from a point)
 - **Minor problem**: avoid by breaking ties in a consistent fashion (e.g., always assign point to "smallest" centroid under some total ordering of vectors)

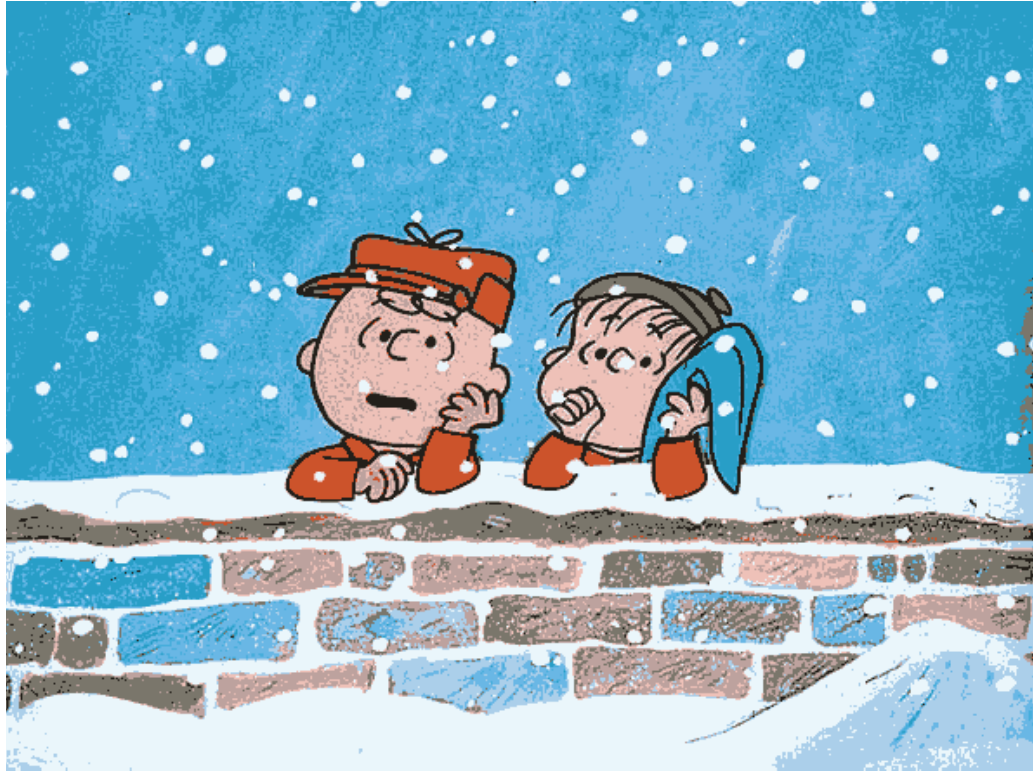
Image compression



Credit:
Dave Blei

- Pixel is vector of red, green, and blue values in $\{0, \dots, 255\}$
- 2048×1536 image is a dataset of 3.1 million vectors, each requiring 24 bits of storage
- Let's compress by clustering pixels with k -means

Vector quantization



Credit:
Dave Blei



- Recovered k means called *codebook*
 - Each *codeword* (after rounding) corresponds to a color
- Compression: replace each image pixel by its codeword
- $\log_2(k)$ bits instead of 24 per pixel (plus small overhead)

Peanuts vector quantization: 2 means

Courtesy of Dave Blei



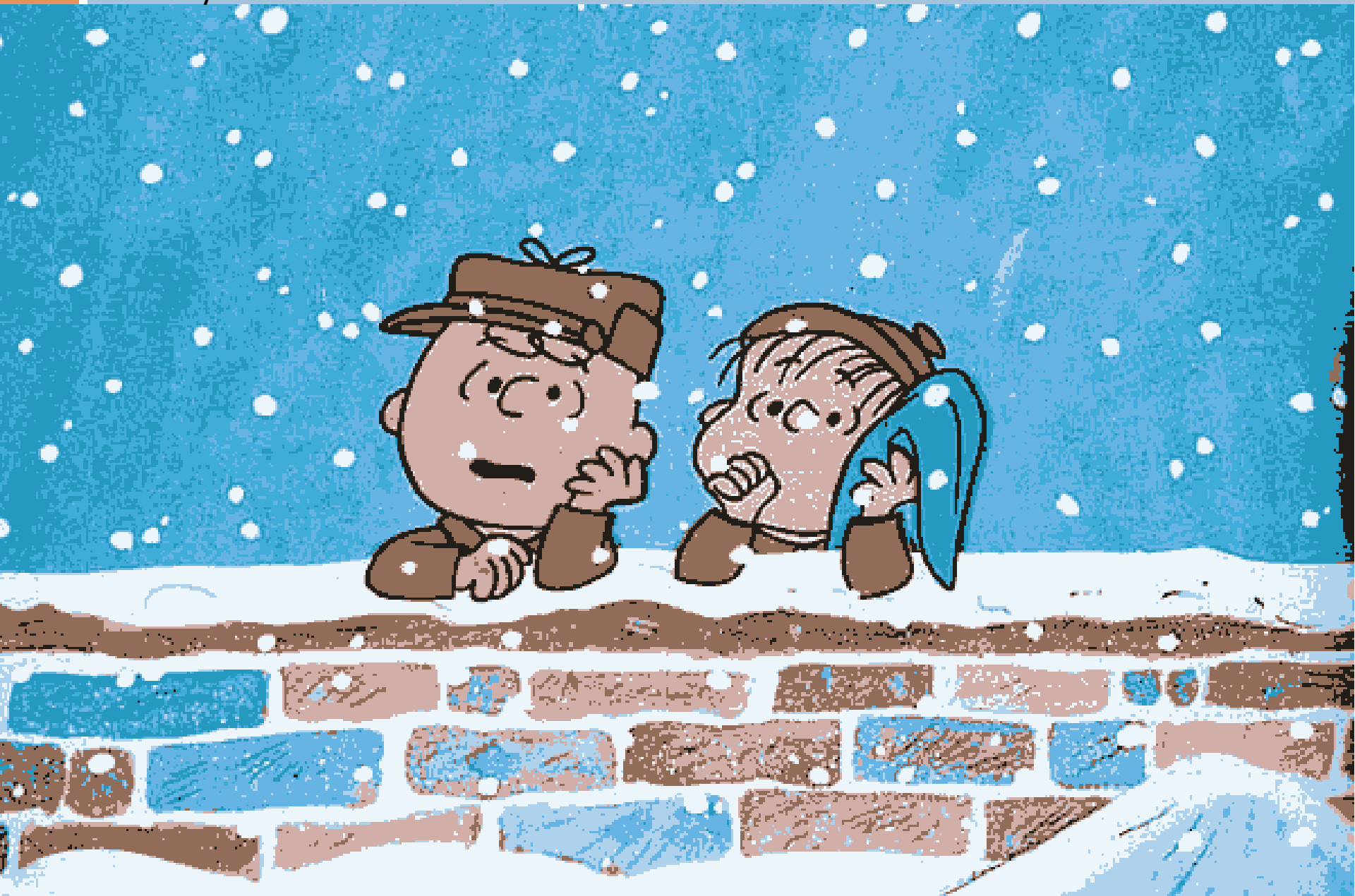
Peanuts vector quantization: 4 means

Courtesy of Dave Blei



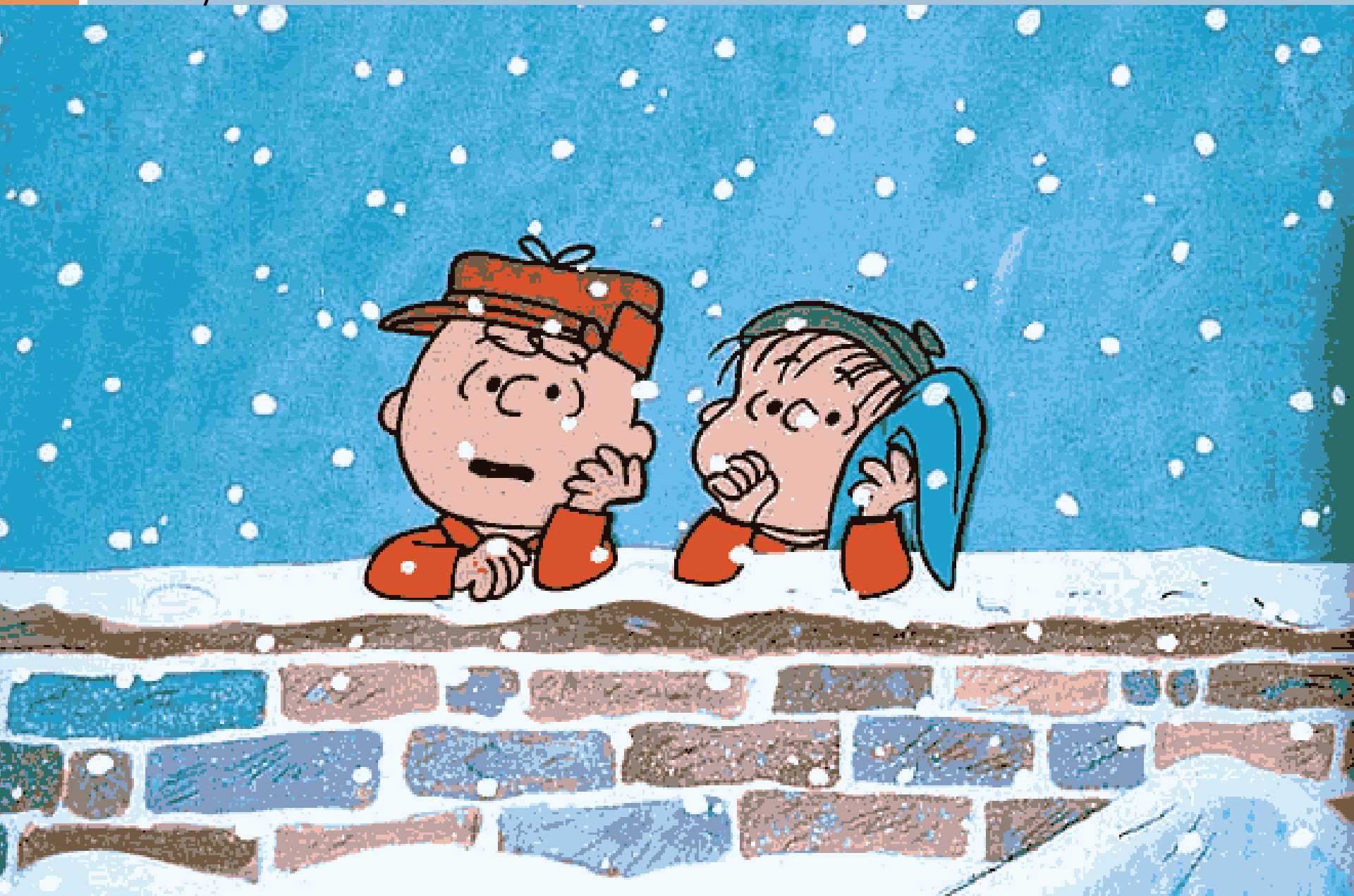
Peanuts vector quantization: 8 means

Courtesy of Dave Blei



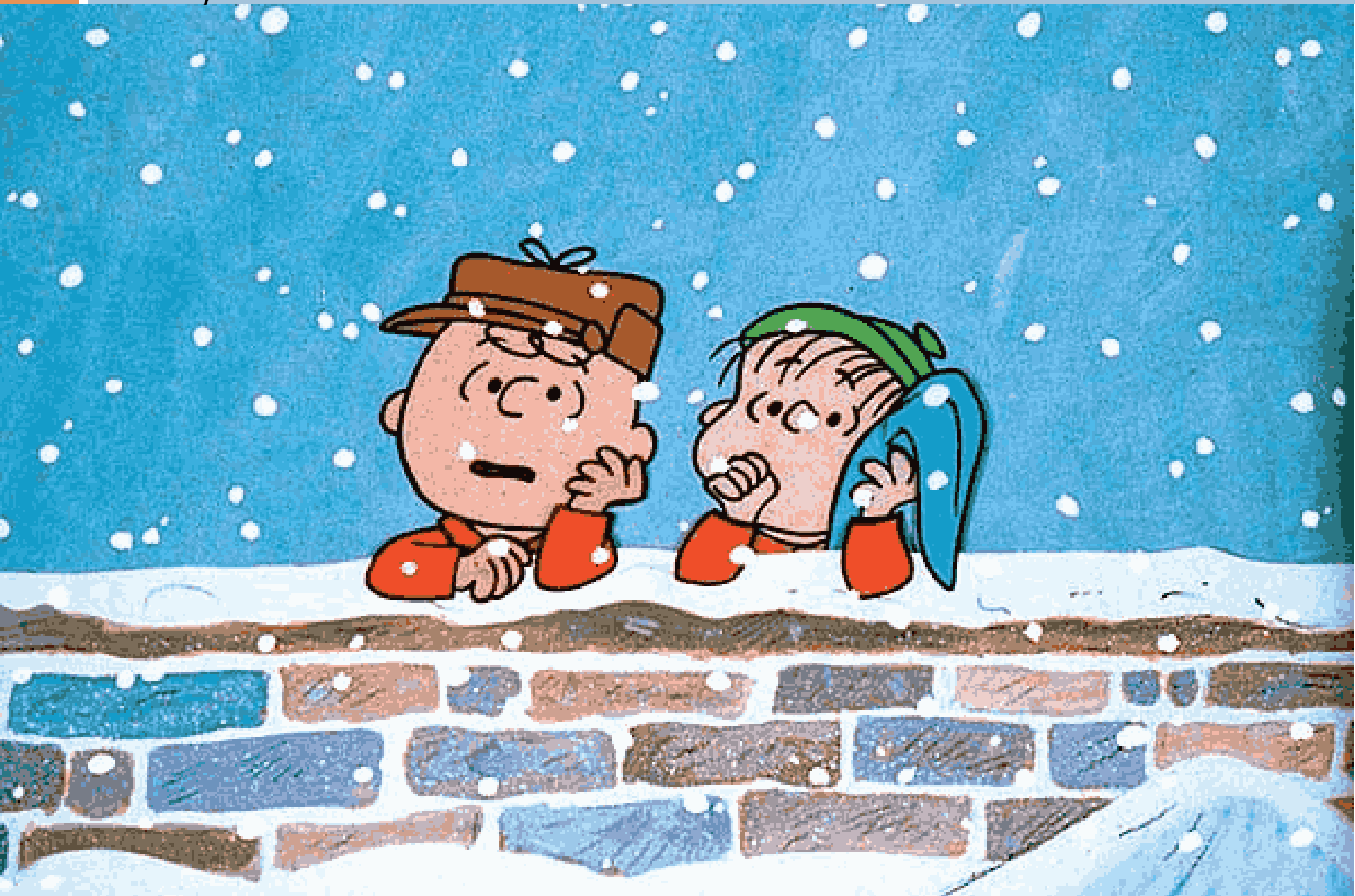
Peanuts Vector Quantization: 16 means

Courtesy of Dave Blei



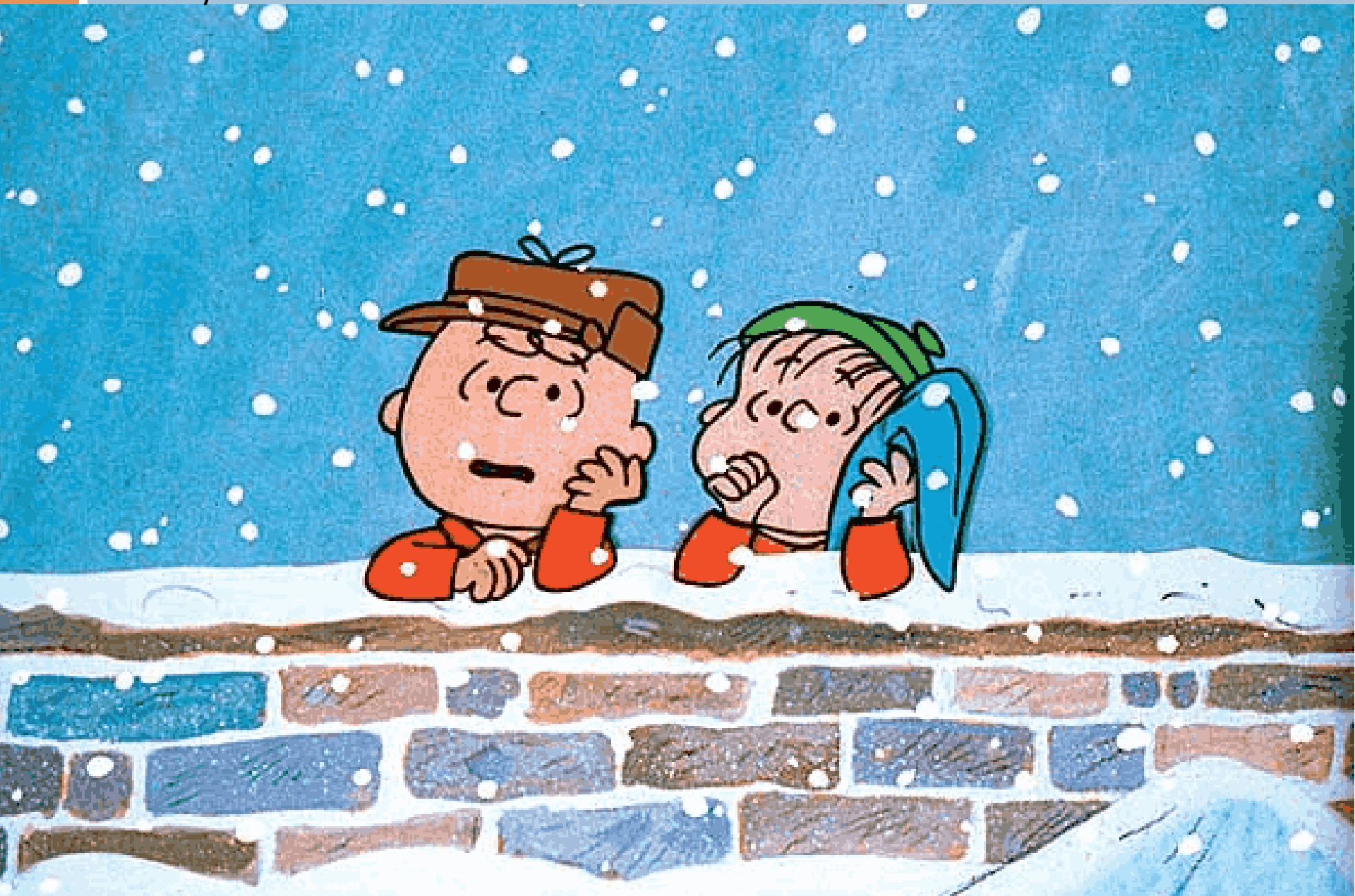
Peanuts Vector Quantization: 32 means

Courtesy of Dave Blei



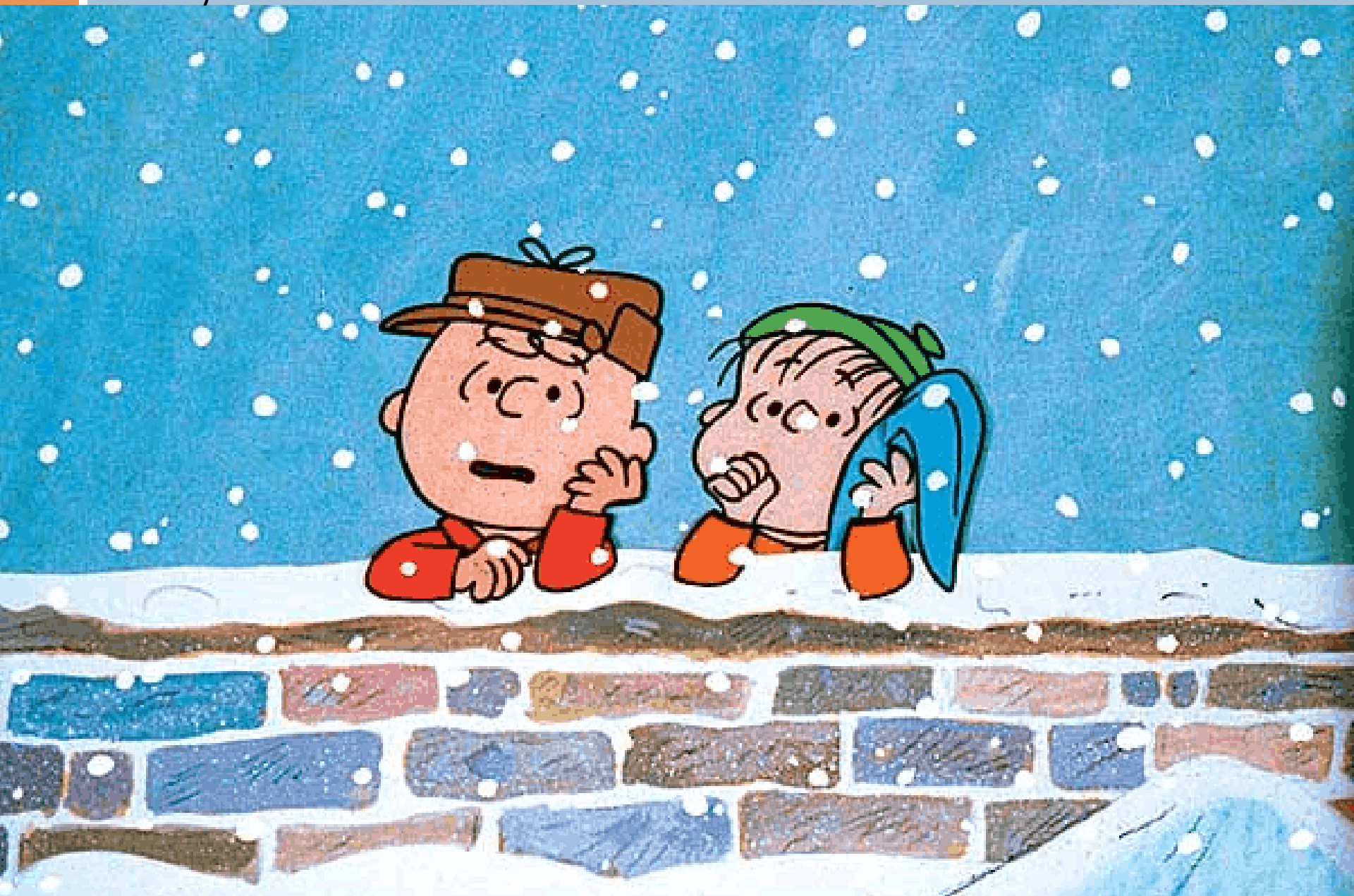
Peanuts vector quantization: 64 means

Courtesy of Dave Blei



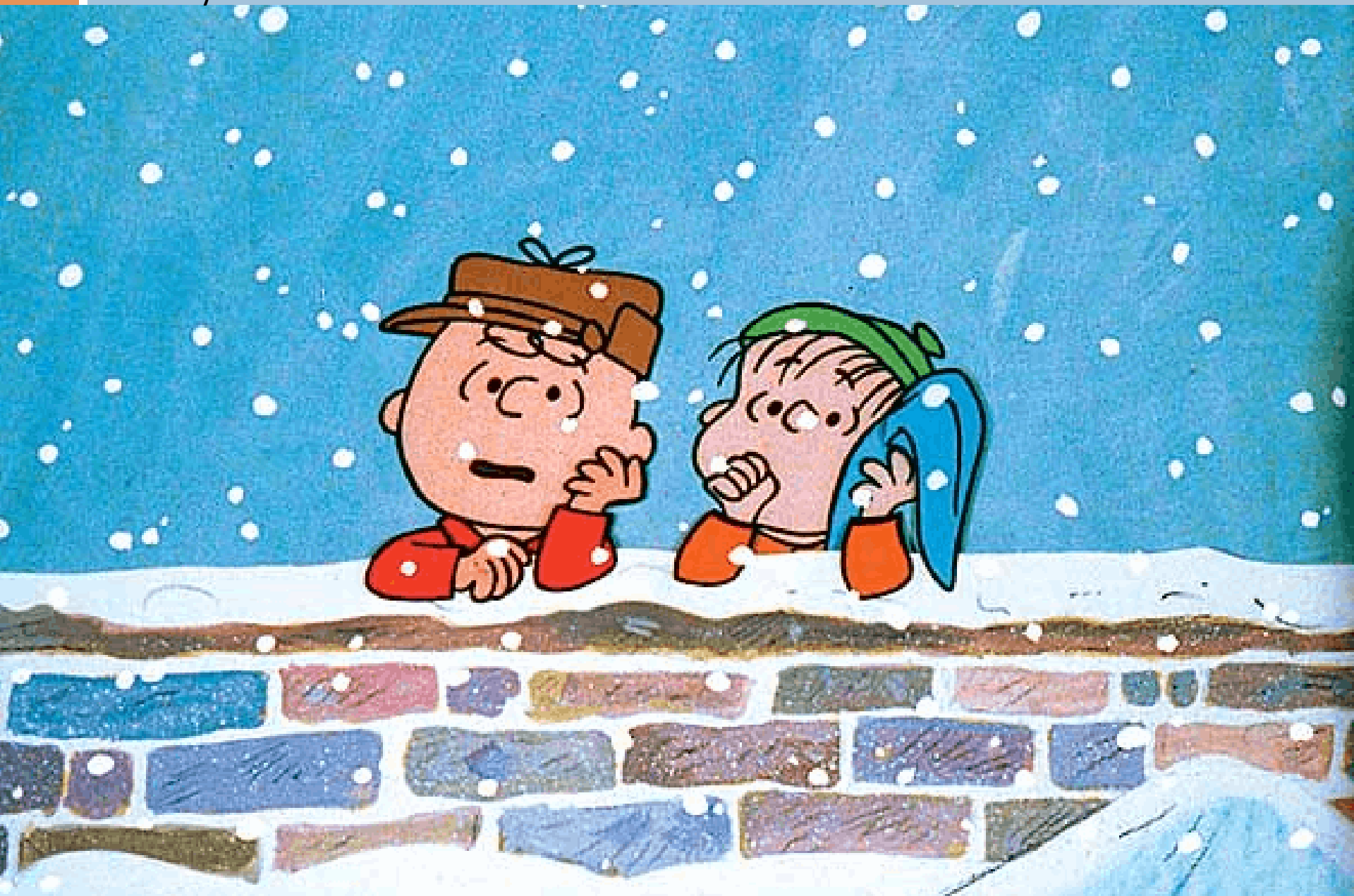
Peanuts vector quantization: 128 means

Courtesy of Dave Blei



Peanuts vector quantization: 256 means

Courtesy of Dave Blei



k-means: Practical considerations

1. Squared Euclidean objective **restrictive**

$$J(z_{1:n}, m_{1:k}) = \sum_{i=1}^n \|x_i - m_{z_i}\|_2^2$$

- Inappropriate for non-quantitative (e.g., categorical) features
- Euclidean distance
 - Sensitive to outliers
 - Ill-suited for features with very different scales / importances

2. **NP-hard** optimization problem

- Lloyd's algorithm **usually** finds **suboptimal solutions**
- Many random restarts often needed for good performance

3. Must **choose k**

4. Running time: **# features x # datapoints x k** per iteration

- Orders of magnitude reductions using space-partitioning data structures like *kd-trees* (e.g., Kanungo et al., 2002, optional reading)

Beyond Euclidean distance

- **Issue:** Squared Euclidean distance in k -means
- **Idea:** Minimize $J_d(z_{1:n}, m_{1:k}) = \sum_{i=1}^n d(x_i, m_{z_i})$
 - Arbitrary dissimilarity / discrepancy measure $d(x, m)$
 - Optimize via coordinate descent as in Lloyd's algorithm
 - Update cluster assignments: $z_{1:n} \leftarrow \arg \min_{z_{1:n}} J_d(z_{1:n}, m_{1:k})$
 - Update cluster representatives: $m_{1:k} \leftarrow \arg \min_{m_{1:k}} J_d(z_{1:n}, m_{1:k})$
 - **Pro:** Applies to all data types and dissimilarity measures
 - **Con:** Updating cluster representatives $m_{1:k}$ may be expensive
- **k -medoids algorithm**
 - Minimize J_d above but constrain each cluster representative to be a datapoint, i.e. $m_j \in \{x_1, \dots, x_n\}$
 - **Pro:** Don't need to store datapoints, only pairwise discrepancies $d(x_i, x_j)$

k-means++

Arthur and Vassilvitskii, 2008 (optional reading)

- **Issues:** Lloyd's algorithm suboptimal, random restarts
- **k-means++:** Improves initialization of Lloyd's algorithm
 - Choose first center m_1 uniformly at random from $\{x_1, \dots, x_n\}$
 - For $j = 2, \dots, k$:
 - Let $D(x)$ = Euclidean distance to closest center previously chosen
 - Choose $m_j = x_i$ with probability proportional to $D(x_i)^2$
 - Run Lloyd's algorithm with this initialization
- **Thm:** $E[\text{objective after } k\text{-means++}] \leq 8(\ln(k) + 2)$ optimal
- In practice: more accurate and faster than k -means alone

k	Average ϕ		Minimum ϕ		Average T	
	k-means	k-means++	k-means	k-means++	k-means	k-means++
10	$3.387 \cdot 10^8$	93.37%	$3.206 \cdot 10^8$	94.40%	63.94	44.49%
25	$3.149 \cdot 10^8$	99.20%	$3.100 \cdot 10^8$	99.32%	257.34	49.19%
50	$3.079 \cdot 10^8$	99.84%	$3.076 \cdot 10^8$	99.87%	917.00	66.70%

Table 3: Experimental results on the *Intrusion* dataset ($n = 494019$, $d = 35$). For **k-means**, we list the actual potential and time in seconds. For **k-means++**, we list the percentage *improvement* over **k-means**.

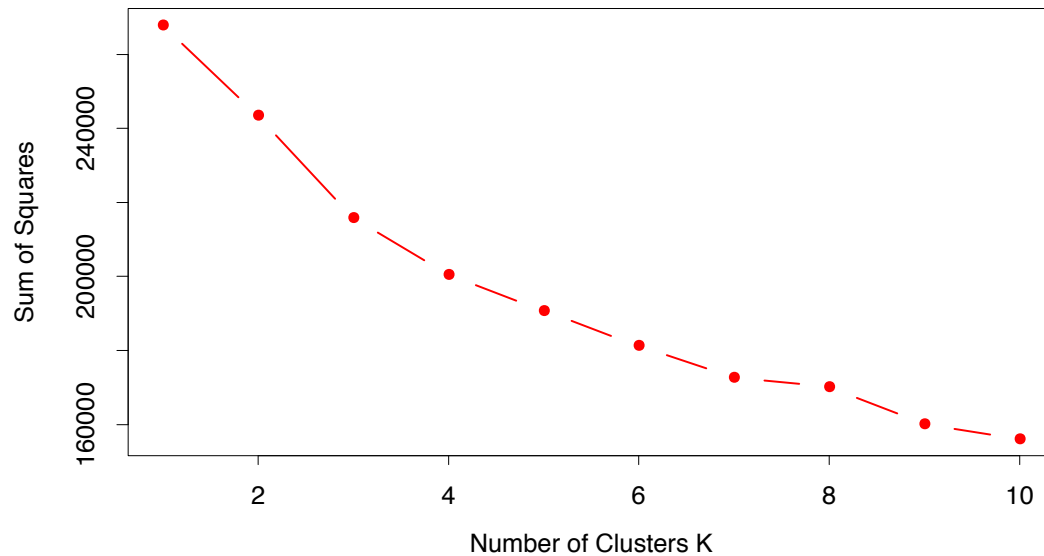
Choosing the number of clusters k

- Some applications determine k
 - Target compression level in vector quantization
 - Funds to develop three new Cheerios flavors
- How do we pick k otherwise?
 - Minimum k -means objective shrinks as k grows: not helpful
 - Evaluate fit of learned centers on **held-out data**?
 - **Problem:** Held-out objective also tends to decrease with k !
 - No agreed-upon solution but many alternatives...
 - **Stability:** Cluster randomly subsampled or perturbed datasets and measure discrepancy between resulting clusterings
 - Choose k to minimize discrepancy

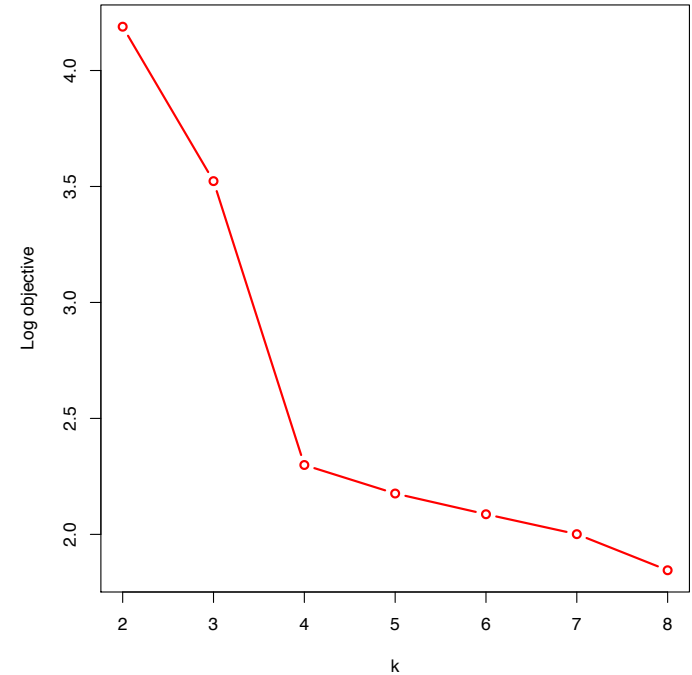
Choosing the number of clusters k

■ Elbow criterion

- Marginal gain in objective may decrease at true / natural value of k
- Not always unambiguously defined



Human tumor microarray data
(Courtesy: Rob Tibshirani)



Simulated data, 4 true clusters
(Courtesy: Dave Blei)

Choosing the number of clusters k

- **Gap statistic** (Tibshirani, Walther, & Hastie, 2001 – optional reading)
 - Let O_k be the objective value of k -means run on $\{x_1, \dots, x_n\}$
 - Let U_k be the objective value of k -means run on n points sampled randomly from the smallest box containing $\{x_1, \dots, x_n\}$
 - Serves as a single cluster null distribution
 - Roughly, choose k to maximize **Gap(k) = E[log(U_k)] – log(O_k)**
 - More precisely, form Monte Carlo estimate of Gap and choose smallest k such that
 $\text{Gap}_{\text{est}}(k) \geq \text{Gap}_{\text{est}}(k+1) - \text{estimate of standard deviation of } \log(U_k)$

Gap statistic: simulated data

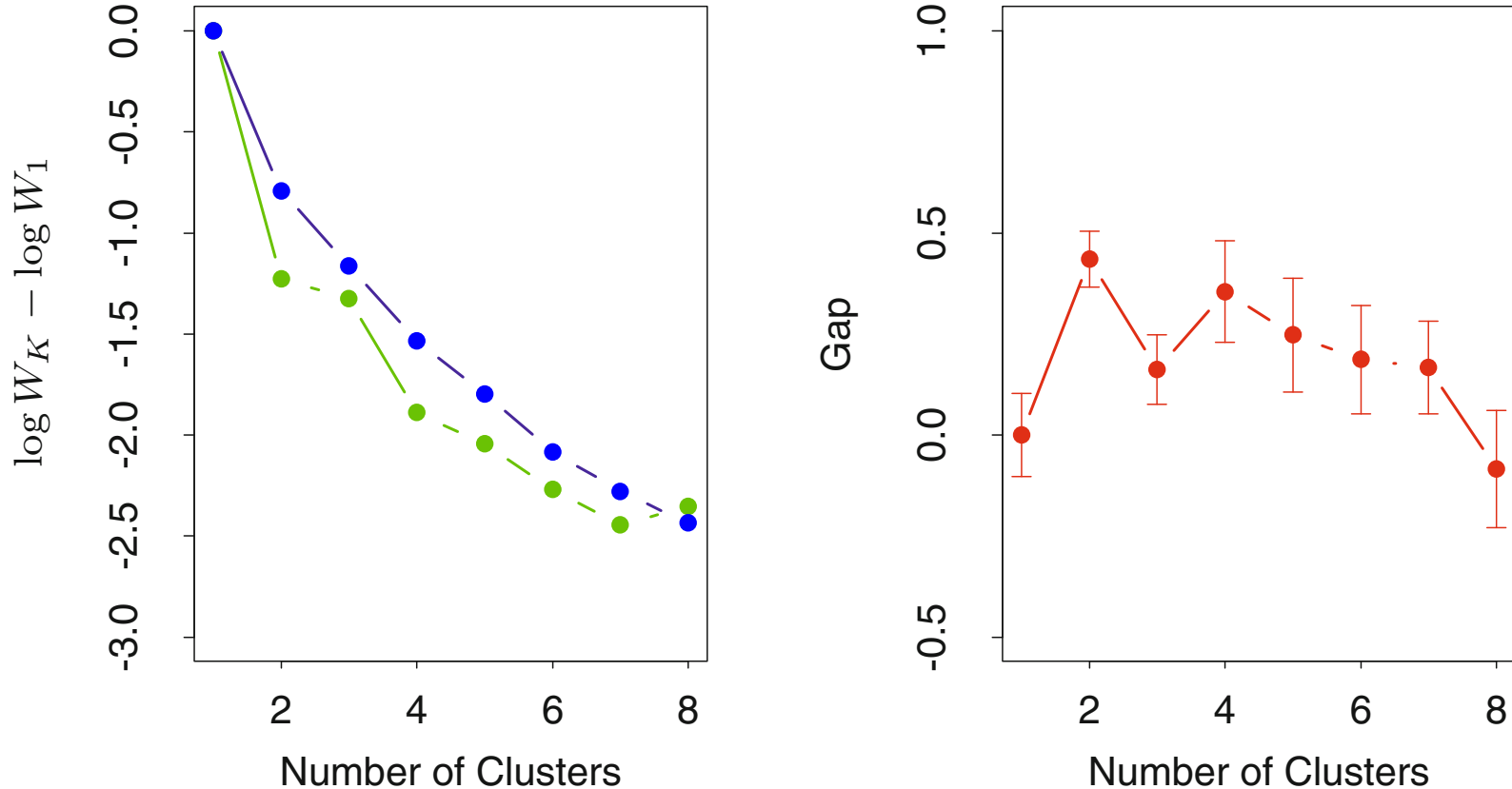


FIGURE 14.11. (Left panel): observed (green) and expected (blue) values of $\log W_K$ for the simulated data of Figure 14.4. Both curves have been translated to equal zero at one cluster. (Right panel): Gap curve, equal to the difference between the observed and expected values of $\log W_K$. The Gap estimate K^* is the smallest K producing a gap within one standard deviation of the gap at $K + 1$; **37** here $K^* = 2$.

Comparing estimates of k

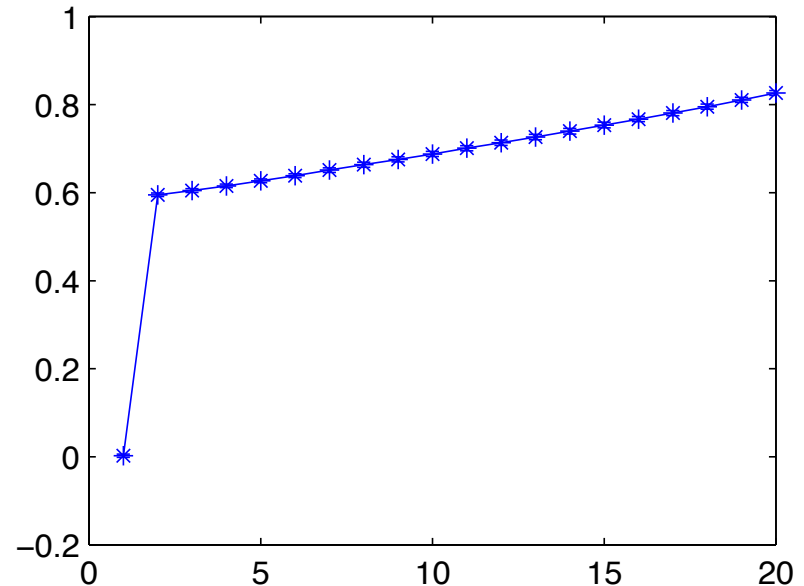
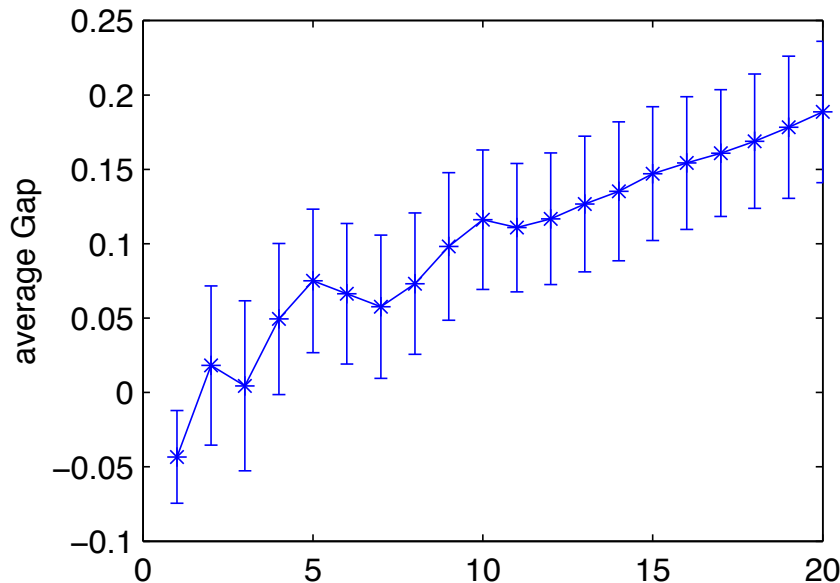
(Tibshirani, Walther, Hastie 2001)

Method	Estimate of number of clusters \hat{k}									
	1	2	3	4	5	6	7	8	9	10
Null model in 2 dimensions										
CH	0*	0	0	10	0	0	3	5	17	15
KL	0*	0	1	5	12	5	13	5	9	0
Hartigan	0*	0	0	0	0	0	0	0	2	48
Silhouette	0*	18	22	10	0	0	0	0	0	0
Gap	42*	7	0	1	0	0	0	0	0	0
Gap/pc	44*	6	0	0	0	0	0	0	0	0
Null model in 10D										
CH	0*	50	0	0	0	0	0	0	0	0
KL	0*	29	5	3	3	2	2	0	0	0
Hartigan	0*	0	1	20	21	6	0	0	0	0
Silhouette	0*	49	1	0	0	0	0	0	0	0
Gap/unif	49*	1	0	0	0	0	0	0	0	0
Gap/pc	50*	0	0	0	0	0	0	0	0	0
Three clusters										
CH	0	0	50*	0	0	0	0	0	0	0
KL	0	0	39*	0	5	1	1	2	0	0
Hartigan	0	0	1*	8	19	13	3	3	2	1
Silhouette	0	0	50*	0	0	0	0	0	0	0
Gap/unif	1	0	49*	0	0	0	0	0	0	0
Gap/pc	2	0	48*	0	0	0	0	0	0	0

Choosing the number of clusters k

■ Gap statistic

- Performs similarly to other leading methods when $k > 1$
- **Pro:** Can detect $k = 1$ (many other methods can't)
- **Con:** Performs poorly in high dimensions



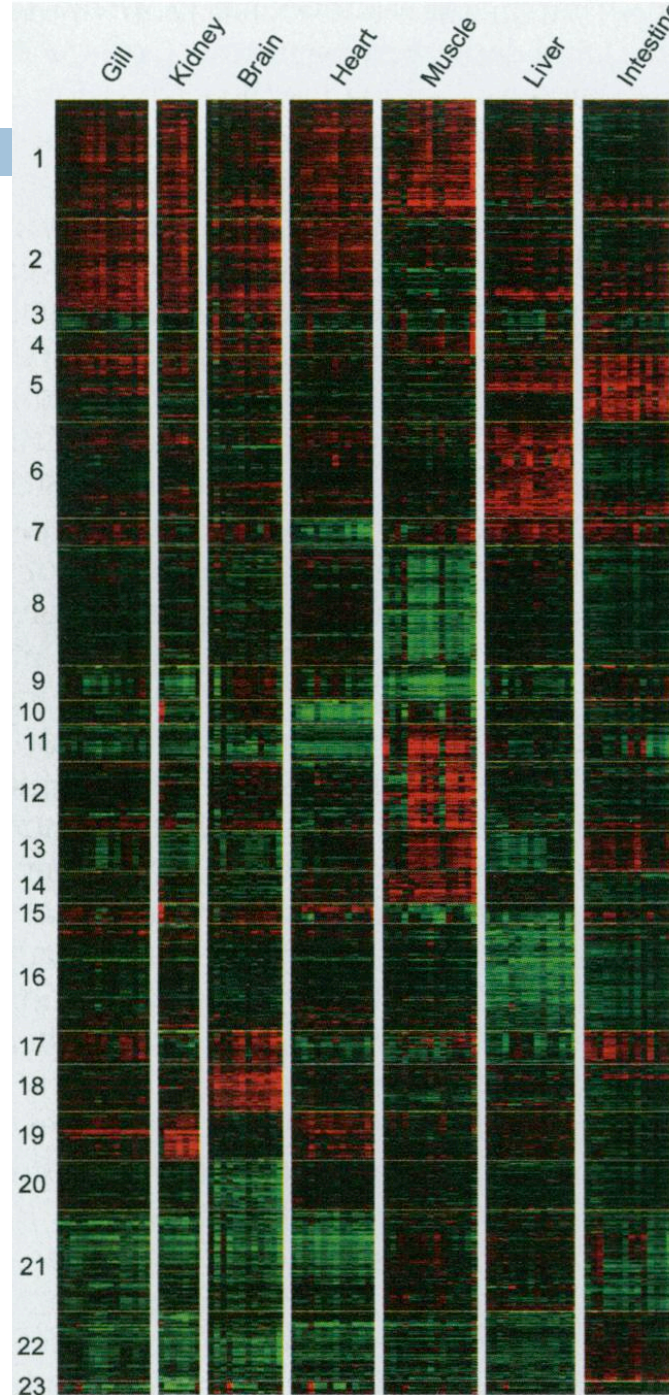
Simulations, true $k = 2$: $p = 2$ (Left), $p = 100$ (right)

(Mohajer et al., 2011: A comparison of Gap statistic definitions with and without logarithm function)

k-means in the wild: Biology

Coping with cold: An integrative, multitissue analysis of the transcriptome of a poikilothermic vertebrate (Gracey et al., 2004)

- Carp exposed to increasing levels of cold
- Genes (rows) clustered using 23-means according to cold response across different tissues
 - No explanation for $k = 23$ given
- Eventually interpreted functional significance of each cluster



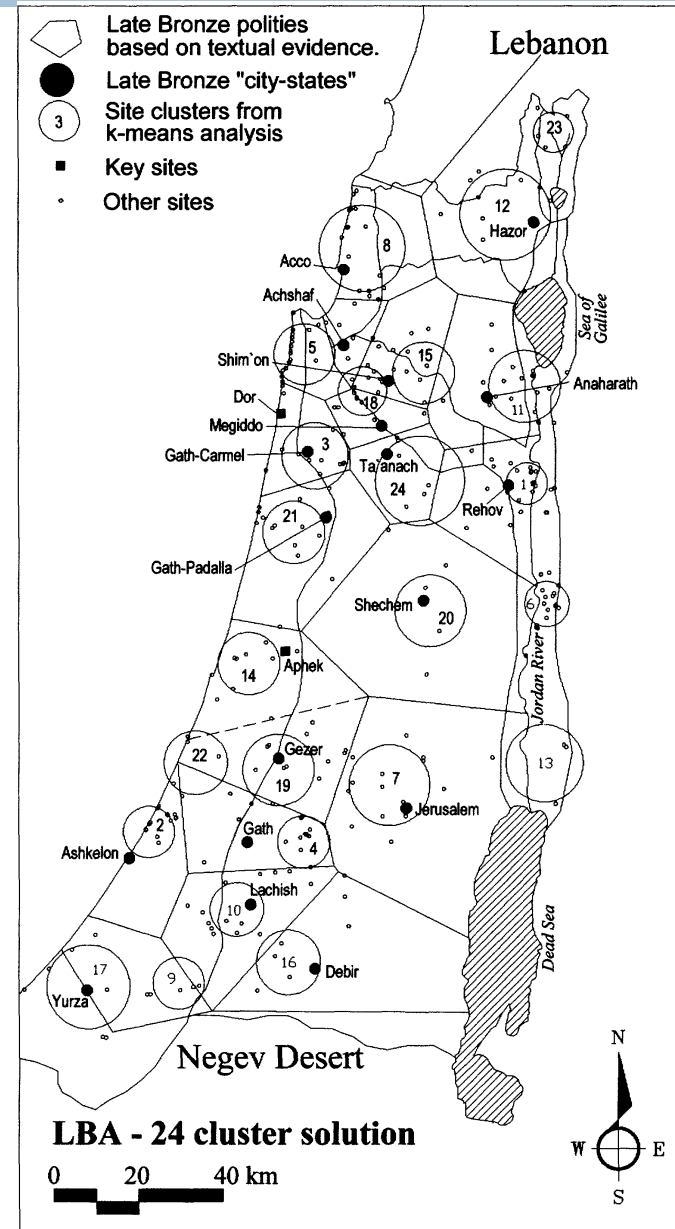
Credit: Dave Blei

k-means in the wild: Archaeology

Credit: Dave Blei

Spatial and Statistical Inference of Late Bronze Age Polities in the Southern Levant (Savage and Falconer, 2003)

- Cluster archaeological site locations in Israel with *k*-means
- k* chosen by comparing to a null distribution based on randomly sampled points
- “Infer a political landscape that corresponds well with many aspects of historical reconstruction and propose new ideas on the configuration and structure of Late Bronze Age [1500-1200 BC] polities”



k-means in the wild: Education

Credit: Dave Blei

Teachers as Sources of Middle School Students' Motivational Identity: Variable-Centered and Person-Centered Analytic Approaches (Murdock and Miller, 2003)

- Clustered 206 eighth-grade students by survey data describing parent academic support, peer academic support, and teacher caring levels
- No clusters centers had above average support for one category and below average support for another; suggests that support classes do not compensate for one another?
- $k = 5$ chosen based on parsimony, heterogeneity, convergence issues, and inspection

k-means in the wild: Education

Credit: Dave Blei

TABLE 3. Five-Cluster Solution: Z scores on Each Clustering Variable

	Cluster 1	Cluster 2	Cluster 3	Cluster 4	Cluster 5
Teacher caring	-.5	-.5 to .5	-.5 to .5	-.5	1.0
Peers' academic support	1.0	-.5	1.0	-.5	-.5 to .5
Parents' academic support	.5	-1.0	-.5 to .5	-.5 to .5	1.0

TABLE 4. Means and Standard Deviations for Each Cluster on Grade 8 Motivational Variables

Cluster	Academic Self-Efficacy		Intrinsic Valuing of Education		Teacher-Rated Effort	
	M	SD	M	SD	M	SD
1. All positive	3.59	.48 ^a	2.99	.55 ^a	3.74	.26 ^a
2. Peer negative, parents very negative	2.44	.66 ^b	2.16	.51 ^b	3.05	.61 ^b
3. Peer positive	3.01	.73 ^c	2.43	.66 ^b	3.26	.66 ^b
4. Negative teacher and peer	2.47	.63 ^b	2.24	.51 ^b	3.17	.59 ^b
5. Positive teacher and parents	3.19	.65 ^c	2.89	.62 ^a	3.54	.47 ^a

k-means: Practical considerations, Part II

- Hard assignments to clusters not stable under small perturbations of data
 - **Mixture modeling** (next time) employs soft assignments
- Gives equal weight to each coordinate and cluster
 - Mixture modeling can relax both assumptions
- Clusters change arbitrarily for different K
 - **Hierarchical clustering** (later) yields nested clusterings
- Works poorly on non-convex clusters
 - **Spectral clustering** (later) well-suited to non-convex clusters

Summary

- Unsupervised learning:
 - **Goal:** Discover hidden structure in data without prior labels or observations of that structure
 - Challenging but necessary
 - Various practical benefits
- Clustering
 - **Goal:** Segment datapoints into similar groups
 - Many applications, many approaches
- *k*-means
 - Simple, popular, canonical approach to clustering
 - Great diversity of applications, including vector quantization
 - Various drawbacks and opportunities for improvement
 - Objective, solution optimality, choice of *k*, running time
 - Various generalizations, including *k*-medoids

Credits

- Parts of this material were adapted from slides by Dave Blei, Sriram Sankararaman, and Robert Tibshirani